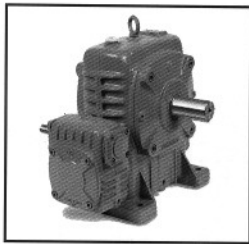


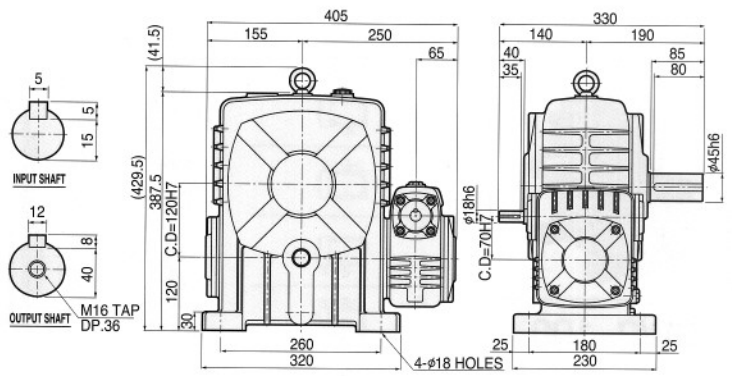
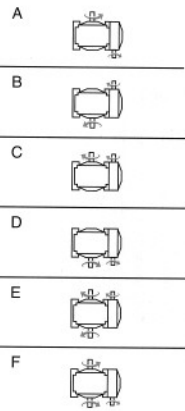
Double Worm Reducer

2단 웜 감속기

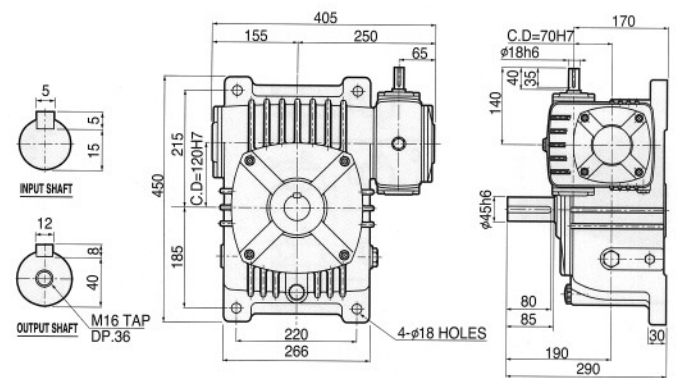
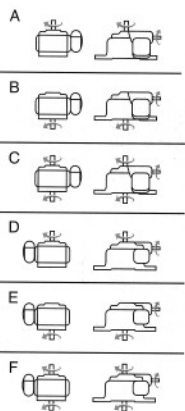
MODEL 축배치 및 회전방향 도 면



DWB-120



DWV-120



III-5

전동능력표

수치는 1일 8~10시간 연속 운전이고 균일 하중의 수치입니다.

| INPUT rpm | 1800 | | | | 1500 | | | | 1200 | | | |
|-----------|----------|-----------|----------------|------------------|----------|-----------|----------------|------------------|----------|-----------|----------------|------------------|
| | INPUT HP | OUTPUT HP | OUTPUT T kgf-m | OUTPUT O.H.L kgf | INPUT HP | OUTPUT HP | OUTPUT T kgf-m | OUTPUT O.H.L kgf | INPUT HP | OUTPUT HP | OUTPUT T kgf-m | OUTPUT O.H.L kgf |
| 1/200 | 2.04 | 1.05 | 84.0 | 618 | 1.72 | 0.87 | 84.0 | 675 | 1.44 | 0.69 | 84.0 | 749 |
| 1/300 | 1.47 | 0.70 | 84.0 | 749 | 1.24 | 0.58 | 84.0 | 814 | 1.01 | 0.45 | 84.0 | 899 |
| 1/400 | 1.15 | 0.52 | 84.0 | 854 | 0.96 | 0.43 | 84.0 | 925 | 0.81 | 0.35 | 84.0 | 1000 |
| 1/500 | 1.03 | 0.42 | 84.0 | 942 | 0.88 | 0.35 | 84.0 | 1000 | 0.72 | 0.28 | 84.0 | 1000 |
| 1/600 | 0.88 | 0.35 | 84.0 | 1000 | 0.75 | 0.29 | 84.0 | 1000 | 0.61 | 0.23 | 84.0 | 1000 |
| 1/800 | 0.93 | 0.26 | 84.0 | 1000 | 0.78 | 0.21 | 84.0 | 1000 | 0.67 | 0.17 | 84.0 | 1000 |
| 1/900 | 0.69 | 0.23 | 84.0 | 1000 | 0.57 | 0.19 | 84.0 | 1000 | 0.47 | 0.15 | 84.0 | 1000 |

| INPUT rpm | 900 | | | | 600 | | | |
|-----------|----------|-----------|----------------|------------------|----------|-----------|----------------|------------------|
| | INPUT HP | OUTPUT HP | OUTPUT T kgf-m | OUTPUT O.H.L kgf | INPUT HP | OUTPUT HP | OUTPUT T kgf-m | OUTPUT O.H.L kgf |
| 1/200 | 1.11 | 0.52 | 84.0 | 854 | 0.79 | 0.35 | 84.0 | 1000 |
| 1/300 | 0.81 | 0.35 | 84.0 | 1000 | 0.56 | 0.23 | 84.0 | 1000 |
| 1/400 | 0.64 | 0.25 | 84.0 | 1000 | 0.44 | 0.17 | 84.0 | 1000 |
| 1/500 | 0.57 | 0.21 | 84.0 | 1000 | 0.40 | 0.14 | 84.0 | 1000 |
| 1/600 | 0.48 | 0.17 | 84.0 | 1000 | 0.33 | 0.11 | 84.0 | 1000 |
| 1/800 | 0.32 | 0.13 | 84.0 | 1000 | 0.20 | 0.08 | 84.0 | 1000 |
| 1/900 | 0.36 | 0.11 | 84.0 | 1000 | 0.25 | 0.07 | 84.0 | 1000 |